

# Cheatsheet

## General

- Getting alpaka: <https://github.com/alpaka-group/alpaka>
- Issue tracker, questions, support: <https://github.com/alpaka-group/alpaka/issues>
- All alpaka names are in namespace alpaka and header file *alpaka/alpaka.hpp*
- This document assumes

```
#include <alpaka/alpaka.hpp>
using namespace alpaka;
```

## Accelerator and Device

### Define in-kernel thread indexing type

```
using Dim = DimInt<constant>;
using Idx = IntegerType;
```

### Define accelerator type (CUDA, OpenMP, etc.)

```
using Acc = AcceleratorType<Dim,Idx>;
```

#### AcceleratorType:

```
AccGpuCudaRt,
AccCpuOmp2Blocks,
AccCpuOmp2Threads,
AccCpuOmp4,
AccCpuTbbBlocks,
AccCpuThreads,
AccCpuFibers,
AccCpuSerial
```

### Select device for the given accelerator by index

```
auto const device = getDevByIdx<Acc>(index);
```

## Queue and Events

### Create a queue for a device

```
using Queue = Queue<Acc, Property>;
auto queue = Queue{device};
```

#### Property:

```
Blocking
NonBlocking
```

### Put a task for execution

```
enqueue(queue, task);
```

### Wait for all operations in the queue

```
wait(queue);
```

### Create an event

```
Event<Queue> event{device};
```

### Put an event to the queue

```
enqueue(queue, event);
```

### Check if the event is completed

```
isComplete(event);
```

### Wait for the event (and all operations put to the same queue before it)

```
wait(event);
```

## Memory

Memory allocation and transfers are symmetric for host and devices, both done via alpaka API

### Create a CPU device for memory allocation on the host side

```
auto const devHost = getDevByIdx<DevCpu>(0u);
```

### Allocate a buffer in host memory

```
Vec<Dim, Idx> extent = value;
using BufHost = Buf<DevHost, DataType, Dim, Idx>;
BufHost bufHost = allocBuf<DataType, Idx>(devHost, extent);
```

### (Optional, affects CPU – GPU memory copies) Prepare it for asynchronous memory copies

```
prepareForAsyncCopy(bufHost);
```

### Get a raw pointer to a buffer initialization, etc.

```
DataType * raw = view::getPtrNative(bufHost);
```

### Allocate a buffer in device memory

```
auto bufDevice = allocBuf<DataType, Idx>(device, extent);
```

### Enqueue a memory copy from host to device

```
memcpy(queue, bufDevice, bufHost, extent);
```

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```
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```

## Kernel Execution

### Automatically select a valid kernel launch configuration

```
Vec<Dim, Idx> const globalThreadExtent = vectorValue;  
Vec<Dim, Idx> const elementsPerThread = vectorValue;  
  
auto autoWorkDiv = getValidWorkDiv<Acc>(  
    device,  
    globalThreadExtent, elementsPerThread,  
    false,  
    GridBlockExtentSubDivRestrictions::Unrestricted);
```

### Manually set a kernel launch configuration

```
Vec<Dim, Idx> const blocksPerGrid = vectorValue;  
Vec<Dim, Idx> const threadsPerBlock = vectorValue;  
Vec<Dim, Idx> const elementsPerThread = vectorValue;  
  
using WorkDiv = WorkDivMembers<Dim, Idx>;  
auto manualWorkDiv = WorkDiv{blocksPerGrid,  
    threadsPerBlock,  
    elementsPerThread};
```

### Instantiate a kernel and create a task that will run it (does not launch it yet)

```
Kernel kernel{argumentsForConstructor};  
auto taskRunKernel = createTaskKernel<Acc>(workDiv, kernel, parameters);
```

acc parameter of the kernel is provided automatically, does not need to be specified here

### Put the kernel for execution

```
enqueue(queue, taskRunKernel);
```

## Kernel Implementation

### Define a kernel as a C++ functor

```
struct Kernel {  
    template<typename Acc>  
    ALPAKA_FN_ACC void operator()(Acc const & acc, parameters) const { ... }  
};
```

ALPAKA\_FN\_ACC is required for kernels and functions called inside, acc is mandatory first parameter, its type is the template parameter

### Access multi-dimensional indices and extents of blocks, threads, and elements

```
auto idx = getIdx<Origin, Unit>(acc);  
auto extent = getWorkDiv<Origin, Unit>(acc);
```

#### Origin:

Grid, Block, Thread

#### Unit:

Blocks, Threads, Elms

### Access components of multi-dimensional indices and extents

```
auto idxX = idx[0];
```

### Linearize multi-dimensional vectors

```
auto linearIdx = mapIdx<1u>(idx, extent);
```

### Allocate static shared memory variable

```
Type & var = declareSharedVar<Type, __COUNTER__>(acc);
```

### Get dynamic shared memory pool, requires the kernel to specialize

```
traits::BlockSharedMemDynSizeBytes  
Type * dynamicSharedMemoryPool = getDynSharedMem<Type>(acc);
```

### Synchronize threads of the same block

```
syncBlockThreads(acc);
```

### Atomic operations

```
auto result = atomicOp<Operation>(acc, arguments);
```

#### Operations:

AtomicAdd, AtomicSub, AtomicMin, AtomicMax, AtomicExch,  
AtomicInc, AtomicDec, AtomicAnd, AtomicOr, AtomicXor, AtomicCas

### Warp-level operations

```
uint64_t result = warp::ballot(acc, idx == 1 || idx == 4);  
assert(result == (1<<1) + (1<<4));  
int32_t valFromSrcLane = warp::shfl(val, srcLane);
```

### Math functions take acc as additional first argument

```
math::sin(acc, argument);
```

Similar for other math functions.

### Generate random numbers

```
auto distribution = rand::distribution::createNormalReal<double>(acc);  
auto generator = rand::generator::createDefault(acc, seed, subsequence);  
auto number = distribution(generator);
```